

QNX

Echtzeitsysteme - Übungen zur Vorlesung

Fabian Scheler, Peter Ulbrich, Niko Böhm

Friedrich-Alexander-Universität Erlangen-Nürnberg
Lehrstuhl Informatik 4 (Verteilte Systeme und Betriebssysteme)
www4.informatik.uni-erlangen.de

8. Februar 2010

About QNX

QNX Architecture

Development with QNX

What is QNX?

- ▶ Real-Time Operating System
- ▶ POSIX-compliant $\leadsto$ UNIX-like
- ▶ μ -Kernel Operating System
- ▶ available for a variety of 32-bit target architectures
 - ▶ x86, MIPS, PowerPC, SH-4 and ARM (ARM, StrongARM, xScale)

History of QNX

1980 Idea was born

- ▶ after an OS lecture at Waterloo University

1980 Quantum Software Systems was founded

1982 first version of QNX

- ▶ target architecture: Intel 8088
- ▶ non-embedded OS

mid 1990s QNX 4

- ▶ POSIX-compliance
- ▶ graphical user interface: PHOTON

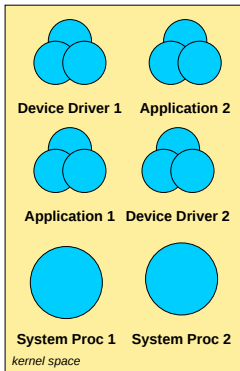
end 1990s QNX Neutrino

- ▶ Linux-like

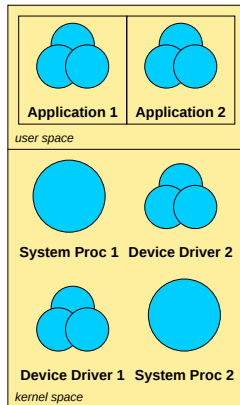
2004 QNX Software Systems taken over by Harman International

Library vs. Monolithic vs. μ -Kernel

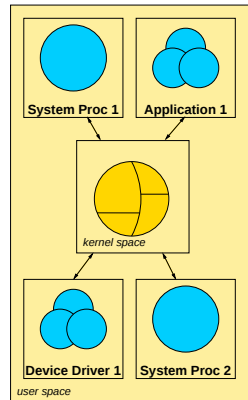
Library



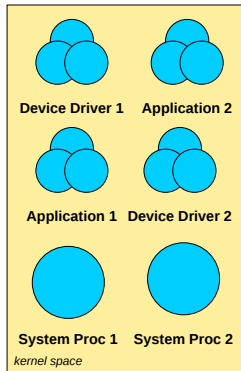
Monolithic



μ -Kernel

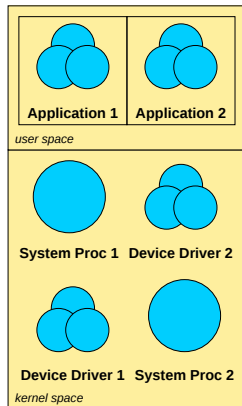


Library-based Executive



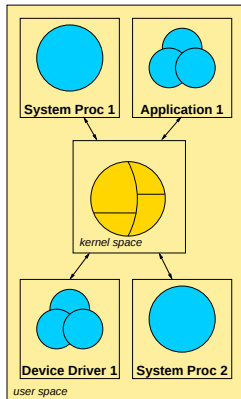
- ▶ single address space
- ▶ no isolation or protection
- ▶ kernel interface: procedure calls
- ▶ small, efficient kernels
- ▶ fault-prone

Monolithic Kernels



- ▶ user space and kernel space
- ▶ separated address spaces
- ▶ isolation and protection
 - ▶ between applications
 - ▶ between applications and the kernel
- ▶ no isolation or protection
 - ▶ kernel and device drivers
- ▶ kernel interface: traps
- ▶ efficient
- ▶ inflexible

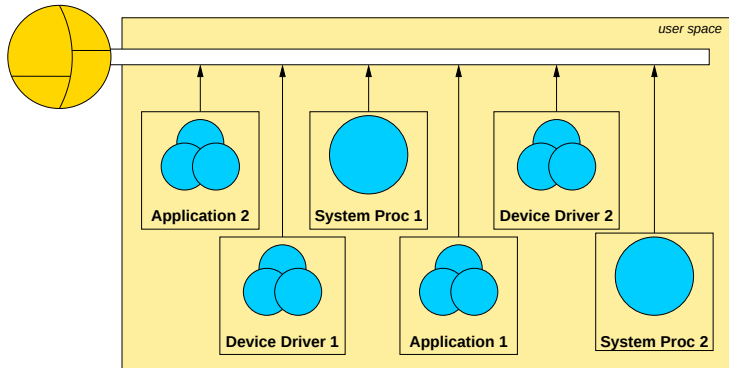
Microkernels



- ▶ user space and kernel space
- ▶ separated address spaces
- ▶ isolation and protection
 - ▶ between applications and
 - ▶ device drivers and
 - ▶ the kernel
- ▶ kernel interface: traps
- ▶ communication: message passing
- ▶ flexible
- ▶ supposed to be inefficient

The Role of the QNX Microkernel

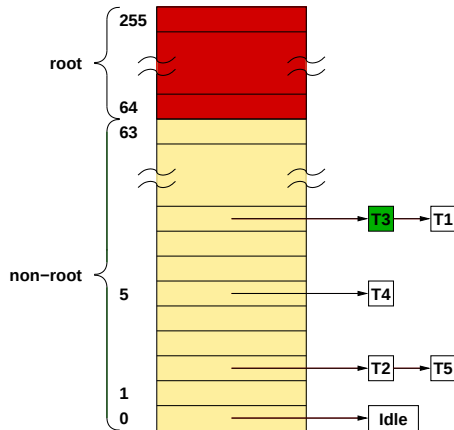
Provides a Software Bus



QNX Microkernel Services

- ▶ thread services (POSIX)
- ▶ signal services (POSIX)
- ▶ message-passing services
- ▶ synchronization services (POSIX)
- ▶ scheduling services (POSIX)
- ▶ timer services (POSIX)
- ▶ process management services

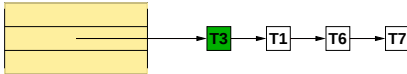
Thread Scheduling



- ▶ priority-driven (256 priorities)
- ▶ full preemptive
- ▶ threads are scheduled globally
- ▶ threads inherit parent priority
- ▶ context switch when a thread
 - ▶ blocks
 - ▶ is preempted
 - ▶ yields
- ▶ scheduling algorithms
 - ▶ FIFO
 - ▶ round-robin
 - ▶ sporadic

Thread Scheduling Algorithms

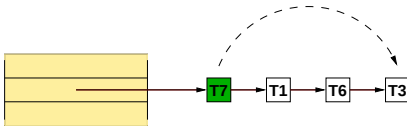
► FIFO



A thread runs until it

- relinquishes control
- is preempted

► Round-robin

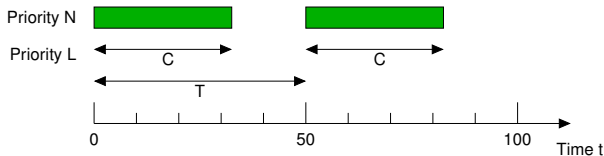


A thread runs until it

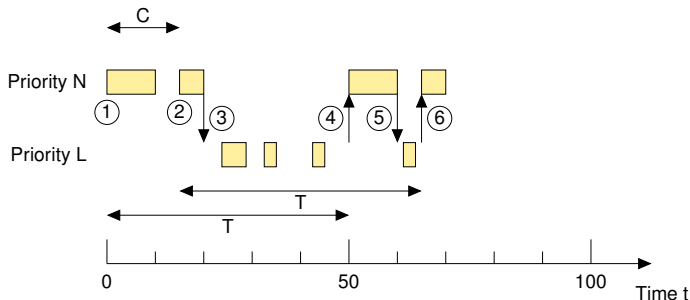
- relinquishes control
- is preempted
- consumes its timeslice

Sporadic Scheduling

- ▶ Sporadic Server
 - ▶ initial budget (C)
 - ▶ foreground: normal priority (N) $\leadsto$ budget is **available**
 - ▶ background: low priority (L) $\leadsto$ budget is **exhausted**
 - ▶ replenishment period (T)
 - ▶ budget is replenished in chunks
 - ▶ number of pending replenishments can be bounded $\leadsto$ overhead
- ▶ equivalent to a periodic thread $T = (T, C)$



Sporadic Scheduling – $D_S = (50ms, 15ms)$

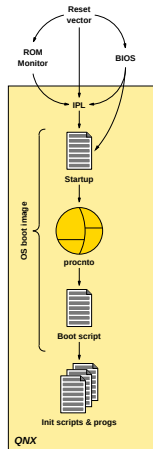


1. thread blocks after 10 ms $\leadsto$ replenishment of 10 ms at 50 ms
2. thread runs again at 15 ms $\leadsto$ replenishment of 5 ms at 65 ms
3. thread exhausts its budget at 20 ms $\leadsto$ drops to low priority L
4. 10 ms of threads budget are replenished $\leadsto$ back to priority N
5. thread exhausts its budget at 60 ms $\leadsto$ drops to low priority L
6. 5 ms of threads budget are replenished $\leadsto$ back to priority N

Thread Synchronization

- ▶ Mutexes (kernel, priority inheritance)
- ▶ Condition Variables (kernel)
- ▶ Barriers (on top of mutexes, Condition Variables)
- ▶ Sleep-on Locks (on top of mutexes, Condition Variables)
- ▶ Reader/Writer Locks (on top of mutexes, Condition Variables)
- ▶ Semaphores (kernel)
- ▶ FIFO Scheduling (kernel)
- ▶ Send/Receive/Reply (kernel)
- ▶ Atomic Operations (processor or emulated by kernel)

Startup



1. Initial programm loader (IPL)

- ▶ configure memory controller, clock
- ▶ setup processor, stack
- ▶ locate OS image
- ▶ load startup program

2. startup program

- ▶ copy and decompress OS image
- ▶ configure hardware
- ▶ determine system configuration
- ▶ establish callout-routines
- ▶ start the OS kernel

3. Operating System Kernel

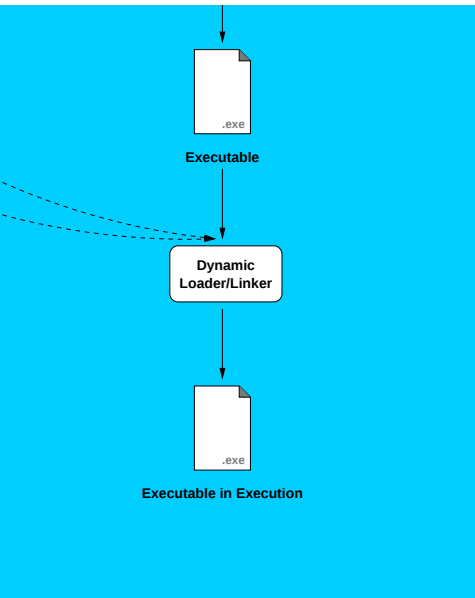
4. Boot Script

5. Applications

Available modules

- ▶ Filesystems (RAM, QNX4, DOS, CD-ROM, FFS3, NFS, CIFS, Ext2, Virtual, ETFS, ...)
- ▶ Character I/O (Console, Serial, Parallel, Pseudo terminals ...)
- ▶ Networking (QNet, TCP/IP)
- ▶ Power Management
- ▶ Photon microGUI
- ▶ XFree86
- ▶ tcsh
- ▶ ...

Development with QNX



Development with QNX

